

2/124  $v_{x=50'} = \sqrt{2g\left(\frac{50}{32.2}\right)^2} = \frac{5}{2}\sqrt{2g} \frac{\text{ft}}{\text{sec}}$   
 $a_n = \frac{v^2}{r}$ , where  $r = \frac{[1 + (\frac{dy}{dx})^2]^{3/2}}{dy/dx} = \frac{[1 + (\frac{3}{200})^2]^{3/2}}{1/200}$   
 $r_{x=50'} = 219 \text{ ft}$   
 $a_n = \frac{25}{2} \cdot 2(32.2)/219 = 1.838 \text{ ft/sec}^2$

2/125  $a_n = v^2/r = 4^2/0.120 = 133.3 \text{ m/s}^2$   
 $a_t = a_n \sin 4^\circ = 133.3 \sin 4^\circ = 9.27 \text{ m/s}^2$   
 with  $a_t$  const.,  $v^2 = v_i^2 + a_t t$ ,  $0 = 4^2 - 9.27 t$   
 $t = \frac{4^2}{9.27} = 2.10 (10^{-3}) \text{ s}$

2/126  $v_0 = 100 \text{ ft/sec}$   
  
 (a)  $a_n = g \cos 30^\circ = \frac{v^2}{r}$   
 $r = \frac{100^2}{g \cos 30^\circ} = 359 \text{ ft}$   
 $\dot{v} = -g \sin 30^\circ = -16.1 \text{ ft/sec}^2$   
 (b)  $a_n = g = \frac{v^2}{r}$   
 $r = \frac{(100 \cos 30^\circ)^2}{32.2} = 233 \text{ ft}$   
 $\dot{v} = 0$

2/127 The time  $t_{\text{top}}$  to apex is found from  
 $v_y = v_{y0} - gt$ ;  $0 = 100 \sin 30^\circ - 32.2 t_{\text{top}}$ ,  $t_{\text{top}} = 1.553 \text{ s}$   
 So,  $t = 1 \text{ sec}$  is before apex and  $t = 2.5 \text{ sec}$  is after.  
 (a)  $t = 1 \text{ sec}$   
 $x = v_x = 100 \cos 30^\circ = 86.6 \text{ ft/sec}$   
 $v_y = 100 \sin 30^\circ - 32.2(1) = 17.8 \text{ ft/sec}$   
 $v = \sqrt{v_x^2 + v_y^2} = 88.4 \text{ ft/sec}$   
 $\theta = \tan^{-1} \frac{v_y}{v_x} = 11.41^\circ$   
 $a_n = g \cos \theta = 32.2 \cos 11.41^\circ = 31.5 \text{ ft/sec}^2$   
 $r = \frac{v^2}{a_n} = \frac{88.4^2}{31.5} = 248 \text{ ft}$   
 $a_t = -g \sin \theta = -32.2 \sin 11.41^\circ = -6.48 \text{ ft/sec}^2$   
 (b)  $t = 2.5 \text{ sec}$   
 $v_x = 86.6 \text{ ft/sec}$   
 $v_y = 100 \sin 30^\circ - 32.2(2.5) = -39.5 \text{ ft/sec}$   
 $v = \sqrt{v_x^2 + v_y^2} = 91.8 \text{ ft/sec}$   
 $\theta = \tan^{-1} \frac{|v_y|}{v_x} = 17.40^\circ$   
 $a_n = g \cos \theta = 32.2 \cos 17.40^\circ = 30.4 \text{ ft/sec}^2$   
 $r = \frac{v^2}{a_n} = \frac{91.8^2}{30.4} = 278 \text{ ft}$   
 $a_t = +g \sin \theta = +32.2 \sin 17.40^\circ = 10.70 \text{ ft/sec}^2$

2/128  $\theta = 1.50^\circ$   
  
 $\dot{v} = a_t = 9.66 \sin 1.50^\circ = 12.90 \text{ m/s}^2$   
 $a_n = g \cos \theta = 9.66 \cos 1.5^\circ = 9.657 \text{ m/s}^2$   
 $a_n = \frac{v^2}{r} \Rightarrow r = \frac{v^2}{a_n} = \frac{(15450/3.6)^2}{9.657}$   
 $r = 1907 \text{ km}$

2/129  $a_n = 0.8g = \frac{v^2}{r} \Rightarrow v = \sqrt{0.8gr}$   
 Car A:  $v_A = \sqrt{0.8(9.8)(88)} = 26.3 \text{ m/s}$   
 Car B:  $v_B = \sqrt{0.8(9.8)(72)} = 23.8 \text{ m/s}$   
 $t_A = \frac{s_A}{v_A} = \frac{\pi(88)}{26.3} = 10.52 \text{ s}$   
 $t_B = \frac{s_B}{v_B} = \frac{\pi(72) + 2(4)}{23.8} = 10.86 \text{ s}$   
 Car A will win the race!

2/130 Evaluate  $y = y_0 + v_{y0}t - \frac{1}{2}gt^2$  at C:  
 $0 = 150 + 0 - \frac{1}{2}(9.8)t^2$ ,  $t = 3.05 \text{ sec}$   
 Evaluate  $x = x_0 + v_{x0}t + \frac{1}{2}a_x t^2$  at C:  
 $120 = 0 + 50(3.05) + \frac{1}{2}a_x(3.05)^2$ ,  $a_x = -7.00 \text{ ft/sec}^2$   
 At B:  $\begin{cases} v_x = v_{x0} + a_x t: v_x = 50 - 7.00t \\ v_y = v_{y0} - gt: |v_y| = 32.2t \end{cases}$   
 Set  $v_x = |v_y|$  to obtain  $t = 1.275 \text{ sec}$   
 So at B:  $v_x = |v_y| = 32.2(1.275) = 41.1 \text{ ft/sec}$   
 The speed at B is  $v = 41.1\sqrt{2} = 58.1 \text{ ft/sec}$   
 $a_n = 32.2 \cos 45^\circ + 7.00 \cos 45^\circ = 27.7 \text{ ft/sec}^2$   
 From  $a_n = \frac{v^2}{r}$   
 $r = \frac{v^2}{a_n} = \frac{(58.1)^2}{27.7} = 121.7 \text{ ft}$

2/131 For  $a_t$  const.,  $v_f^2 = v_i^2 + 2a_t s_{\text{acc}}$   
 $v_f^2 = \frac{250^2}{3.6^2} + 0$ ,  $v_i^2 = \frac{250^2}{3.6^2}$ ,  $a_t = \frac{(1500)^2 - (250)^2}{(16)^2 \cdot 2(1000)} = -2.89 \text{ m/s}^2$   
 $v_B^2 = v_A^2 + 2a_t s_{\text{acc}} = \left(\frac{1500}{3.6}\right)^2 + 2(-2.89)(1000) = 3154 \text{ (m/s)}^2$   
 $v_B = 56.2 \text{ m/s}$   
 at B,  $a_t = \frac{v_B^2}{r} = \frac{56.2^2}{1000} = 3.17 \text{ m/s}^2$   
 $a = \sqrt{a_n^2 + a_t^2} = \sqrt{(2.89)^2 + (3.17)^2} = 4.32 \text{ m/s}^2$

# Meriam Kraige Dynamics 6th Edition Solution

**Lei Huang**



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**Essentials of Dynamics and Vibrations** John Billingsley,2025-03-02 This updated second edition brings the complex mathematics of three dimensional dynamics to life with real time simulations making the equations easier to grasp Covering core topics in mechanical engineering such as kinematics dynamics vibration analysis gyroscopes gears and Euler s equations the book offers a clear and engaging approach for students professionals and enthusiasts alike With a focus on practical applications it explains everything from the laws of motion to motors and mechanisms providing a comprehensive understanding of mechanical systems New to this edition is a chapter on Power Energy and Perpetual Motion which reveals intriguing comparisons such as the energy needed to lift water versus the heat required to warm it The final chapter Rocket Science has been expanded to debunk myths about black holes and gravity humorously addressing science fiction misconceptions while proposing exciting space projects

**700 Solved Problems In Vector Mechanics for Engineers: Dynamics** Joseph F. Shelley,1991-04 Suitable for 2nd year college and university engineering students this book provides them with a source of problems with solutions in vector mechanics that covers various aspects of the basic course It offers the comprehensive solved problem reference in the subject It also provides the student with the problem solving drill

Solving Dynamics Problems in MathCad A Supplement to Accompany Engineering Mechanics: Dynamics, 5th Edition by Meriam & Kraige Brian Harper,2001-11-26 If MathCad is the computer algebra system you need to use for your engineering calculations and graphical output Harper s Solving Dynamics Problems in MathCad is the reference that will be a valuable tutorial for your studies Written as a guidebook for students taking the Engineering Mechanics course it will help you with your engineering assignments throughout the course Over the past 50 years Meriam Kraige s Engineering Mechanics Dynamics has established a highly respected tradition of Excellence A Tradition that emphasizes accuracy rigor clarity and applications Now completely revised redesigned and modernized the new fifth edition of this classic text builds on these strengths adding new problems and a more accessible student friendly presentation

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primarily of large and small bodies in oceans You will be introduced to fundamentals such as vector calculus Fourier analysis and ordinary and partial differential equations Then you ll be taken through dimensional analysis of marine systems viscous and inviscid flow around structures surface waves and floating bodies in waves Real life applications are discussed and end of chapter problems help ensure full understanding Students and practicing engineers will find this an invaluable resource for developing problem solving and design skills in a challenging ocean environment through the use of engineering mathematics

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Tianjian Ji CEng FISTructE FHEA is Reader in Structural Engineering at the University of Manchester UK He received the Award for Excellence in Structural Engineering Education from the Institution of Structural Engineers UK in 2014 and the Teaching Excellence Award from the University of Manchester in 2016 He is the primary author of Understanding and Using Structural Concepts 2nd edition also published by Taylor Francis     **Books in Print Supplement** ,1994     *Books in Print* ,1977     **Engineering Mechanics, Dynamics, Study Guide** J. L. Meriam,L. G. Kraige,1997-03-21 This concise and authoritative book emphasizes basic principles and problem formulation It illustrates both the cohesiveness of the relatively few fundamental ideas in this area and the great variety of problems these ideas solve All of the problems address principles and procedures inherent in the design and analysis of engineering structures and mechanical systems with many of the problems referring explicitly to design considerations     Proceedings American Society for Engineering Education. Conference,1993     **Emerging Technologies in Fluids, Structures, and Fluid/structure Interactions** ,2002

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