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Theory and Practice
Using MATLAB®



Mohinder S. Grewal
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Mohinder S. Grewal, Angus P. Andrews



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Kalman Filtering Prentice Hall PTR, 1993-01-01

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Artificial Intelligence and Its Applications Brahim Lejdel, Eliseo Clementini, Louai Alarabi, 2022-03-11 This book contains the proceedings of the second edition of the international Conference on Artificial Intelligence and its Applications AIAP 21 This edition aims to bring together leading academic scientists international researchers and practitioners to exchange and share their experiences and research results on all aspects of Artificial Intelligence It also provides an interdisciplinary platform for researchers practitioners and students to present and discuss the most recent innovations trends and concerns as well as practical challenges encountered and solutions adopted in the fields of Artificial Intelligence This international conference offers an opportunity to bridge the gap between the Artificial Intelligence research community and people from the industry or working in other research areas including smart cities big data cloud computing social networks and energy

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Navigation Satellite Systems, Inertial Navigation, and Integration Mohinder S. Grewal, Angus P. Andrews, Chris G. Bartone, 2015-03-11 An updated guide to GNSS and INS and solutions to real world GNSS INS problems with Kalman filtering Written by recognized authorities in the field this third edition of a landmark work provides engineers computer scientists and others with a working familiarity of the theory and contemporary applications of Global Navigation Satellite Systems GNSS Inertial Navigational Systems and Kalman filters Throughout the focus is on solving real world problems with an emphasis on the effective use of state of the art integration techniques for those systems especially the application of Kalman filtering To that end the authors explore the various subtleties common failures and inherent limitations of the theory as it applies to real world situations and provide numerous detailed application examples and practice problems including GNSS aided INS tightly and loosely coupled modeling of gyros and accelerometers and SBAS and GBAS Drawing upon their many years of experience with GNSS INS and the Kalman filter the authors present numerous design and implementation techniques not found in other professional references The Third Edition includes Updates on the upgrades in existing GNSS and other systems currently under development Expanded coverage of basic principles of antenna design and practical antenna design solutions Expanded coverage of basic principles of receiver design and an update of the foundations for code and carrier acquisition and tracking within a GNSS receiver Expanded coverage of inertial navigation its history its technology and the mathematical models and methods used in its implementation Derivations of dynamic models for the propagation of inertial navigation errors including the effects of drifting sensor compensation parameters Greatly expanded coverage of GNSS INS integration including derivation of a unified GNSS INS integration model its MATLAB implementations and performance evaluation under simulated dynamic conditions The companion website includes updated background material additional MATLAB scripts for simulating GNSS only and integrated GNSS INS navigation satellite position determination calculation of ionosphere delays and dilution of precision

Bayesian Signal Processing James V. Candy, 2016-06-20 Presents the Bayesian approach to statistical signal processing for a variety of useful model sets This book aims to give readers a unified Bayesian treatment starting from the basics Bayes rule to the more advanced Monte Carlo sampling evolving to the next generation model based techniques sequential Monte Carlo sampling This next edition incorporates a new chapter on Sequential Bayesian Detection a new section on Ensemble Kalman Filters as well as an expansion of Case Studies that detail Bayesian solutions for a variety of applications These studies illustrate Bayesian approaches to real world problems incorporating detailed particle filter designs adaptive particle filters and sequential Bayesian detectors In addition to these major developments a variety of sections are expanded to fill in the gaps of the first edition Here metrics for particle filter PF designs with emphasis on classical sanity testing lead to ensemble techniques as a basic requirement for performance analysis The expansion of information theory metrics and their application to PF designs is fully developed and applied These expansions of the book have been updated to provide a more cohesive discussion of

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