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comprehensive and definitive reference to statics and dynamics of solids and structures including mechanics of materials structural mechanics elasticity rigid body dynamics vibrations structural dynamics and structural controls This text integrates the development of fundamental theories formulas and mathematical models with user friendly interactive computer programs written in the powerful and popular MATLAB This unique merger of technical referencing and interactive computing allows instant solution of a variety of engineering problems and in depth exploration of the physics of deformation stress and motion by analysis simulation graphics and animation This book is ideal for both professionals and students dealing with aerospace mechanical and civil engineering as well as naval architecture biomechanics robotics and mechatronics For engineers and specialists the book is a valuable resource and handy design tool in research and development For engineering students at both undergraduate and graduate levels the book serves as a useful study guide and powerful learning aid in many courses And for instructors the book offers an easy and efficient approach to curriculum development and teaching innovation Combines knowledge of solid mechanics including both statics and dynamics with relevant mathematical physics and offers a viable solution scheme Will help the reader better integrate and understand the physical principles of classical mechanics the applied mathematics of solid mechanics and computer methods The Matlab programs will allow professional engineers to develop a wider range of complex engineering analytical problems using closed solution methods to test against numerical and other open ended methods Allows for solution of higher order problems at earlier engineering level than traditional textbook approaches *Books in Print* ,1977

Intelligent Robotics and Applications Jangmyung Lee,Min Cheol Lee,Honghai Liu,Jee-Hwan Ryu,2013-08-23 This two volume set LNAI 8102 and LNAI 8103 constitutes the refereed proceedings of the 6th International Conference on Intelligent Robotics and Applications ICIRA 2013 held in Busan South Korea in September 2013 The 147 revised full papers presented were carefully reviewed and selected from 184 submissions The papers discuss various topics from intelligent robotics automation and mechatronics with particular emphasis on technical challenges associated with varied applications such as biomedical application industrial automation surveillance and sustainable mobility

Engineering Mechanics, Dynamics, Study Guide J. L. Meriam,L. G. Kraige,1997-03-21 This concise and authoritative book emphasizes basic principles and problem formulation It illustrates both the cohesiveness of the relatively few fundamental ideas in this area and the great variety of problems these ideas solve All of the problems address principles and procedures inherent in the design and analysis of engineering structures and mechanical systems with many of the problems referring explicitly to design considerations

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Engineering Metrology for Pedestrian Falls Prevention and Protection In-Ju Kim,2022-03-25 This book explains how to improve the validity reliability and repeatability of slip resistance assessments amongst a range of shoes

floors and environments from an engineering metrology viewpoint covering theoretical and experimental aspects of slip resistance mechanics and mechanisms Pedestrian falls resulting from slips or falls are one of the foremost causes of fatal and non fatal injuries that limit people s functionality There have been prolonged efforts globally to identify and understand their main causes and reduce their frequency and severity This book deals with large volumes of information on tribological characteristics such as friction and wear behaviours of the shoes and floors and their interactive impacts on slip resistance performances Readers are introduced to theoretical concepts and models and collected evidence on slip resistance properties amongst a range of shoe and floor types and materials under various ambulatory settings These approaches can be used to develop secure design strategies against fall incidents and provide a great step forward to build safer shoes floors and walking working environments for industries and communities around the world The book includes many case studies

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