

Line Follower Robot Project Report Details

S Ashworth

Line Follower Robot Project Report Details:

Digital control methods for a line following robot Steffen Block, 2003-12-09 Inhaltsangabe Abstract The project aim was to a built a robot controlled by a PIC microcontroller to follow a line completely autonomously and as quickly as possible The robot meets the requirements from the RoboRama Contest followed a T shape course and obtained more safety features Different kinds of design features and digital algorithms were developed and tested in order to achieve the best results Applied project management techniques and used key skills guaranteed the successful completion of the project in the design and construction of hardware and software technologies The hardware was based on a block structure with infrared sensors at the front of the vehicle Their analogue signals were transferred to digital logic with a comparator This information used a PIC 16F84A microcontroller to control the movement and direction of the robot with pulse width modulation PWM All parts were mounted on a chassis implemented with a mechanical construction set Batteries of 9V provided the necessary power supply Adjustments were done through iterative steps to come to the final result of the robot system The main adapted design feature was the motor and steering system First of all a separate servomotor for the steering and a single DC motor for the forward movement was fixed Through implemented and first testing steps this resolution lacked the required performance Hence the design changed to two DC motors which offered a satisfactory solution The electronic circuit was designed with the computer aided design tool Proteus and executed as a strip line board The software algorithm development started with the truth table to reduce the possible events from thirty two to the eleven applied conditions The generated flowchart gave the program a structure and applied the truth table decision in different PWM generations Finally the software was written in assembler language and implemented on the PIC Inhaltsverzeichnis Table of Contents iTitlei iiAbstractii iiiAcknowledgementsiii ivList of Figuresiv vList of Tablesvi viList of Abbreviationsvii viiList of Symbolsix viiiTable of Contentsx 1 Introduction1 1 1Project Aims2 1 2RoboRama Rules2 2 Specification and Analysis5 2 1Specification of the project 5 2 1 1 Research and definition for the project 5 2 1 2 Resources management 7 2 2 Project time plan 8 3 Design of the robot9 3 1Design of the electronic hardware11 3 1 1Sensors OPD 70911 3 1 2Comparator **Futuristic Sustainable** Energy & Technology Rajesh Singh, Anita Gehlot, P.S. Ranjit, Dolly Sharma, 2022-06-07 Futuristic Sustainable Energy and Technology provides a structured overview of the concept of Futuristic Sustainable Energy and Technology It also explores the promotion of the sustainable development of renewable energy from the perspectives of technology modelling application sustainability and policy This book is dedicated to the advancement of energy efficiency to mitigate consumption ensure and replenish expand and reuse elective energy supplies and to replicate the damage caused by previous energy initiatives This book has offered a large stage of experimentation for practitioners experts researchers and teachers to incorporate and analyze their latest developments as well as the trends and difficulties encountered and the ongoing evolution of the stage in these areas **Government Reports Announcements & Index** ,1988 Robotics and Factories of the Future S.N.

Dwivedi, 1984-12 An International Conference on Robotics and Factories of the Future was held on December 4 7 1984 in Charlotte North Carolina USA The development of technology and the status as it stands today is highly multidisciplinary and complex in nature It has added new dimensions and challenges in the development of factories of the future Thus it calls upon an integrated approach of technological economic and sociological impacts of robots and computers in factories of the future Sessions in this conference included Planning of Automation Future Trends M E Merchant Metcut Research Cincinnati Ohio Stellio Demark ASEA Robotics Milwaukee Wisconsin Stanley J Polcyn Unimation Inc Danbury Connecticut Carl Ruoff Jet Propulsion Lab Pasadena California Joseph Tulkoff Lockheed Georgia Company Marietta Georgia N M Swani Indian Institute of Technology Delhi India James R Barrett Computer Vision Bedford Maryland Hadi A Akeel GMF Robotics Troy Michigan Iohn M **Documentation Abstracts** ,1997 Sm Accounting Information Syst George H. Bodnar, 1998 Government **Reports Announcements & Index**, 1989 British Reports, Translations and Theses British Library. Document Supply Centre, 1991 Scientific and Technical Aerospace Reports, 1989 **Euro Abstracts** ,1997 Government Reports Index .1975 Government Reports Annual Index ,1994 UNIX Review ,1986-07 Database Journal ,1977

Programming and Customizing the OOPic Microcontroller Dennis Clark, 2003 this authoritative guide delves deeply into this groundbreaking technology and delivers a programming guide and application notes dedicated to the OOPic environment This title includes a full object listing as well as an IDE Integrated Development Interface hardware and software guide and a CD OM with all project and experiment codes that you incorporate to customise your own projects Stay ahead of the robotics curve tap into the power of OOPic microcontrollers with this indispensable volume

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